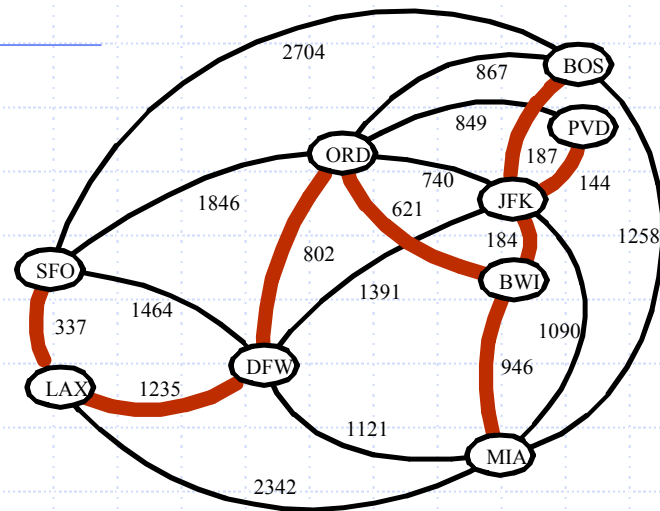
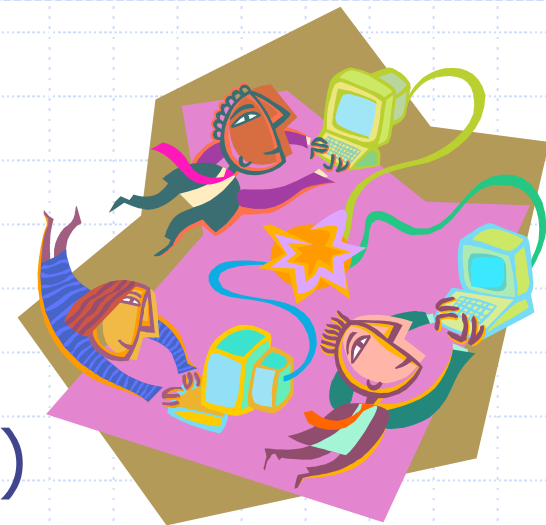


Minimum Spanning Trees



Outline and Reading



- ◆ Minimum Spanning Trees (§12.7)
 - Definitions
 - A crucial fact
- ◆ The Prim-Jarnik Algorithm (§12.7.2)
- ◆ Kruskal's Algorithm (§12.7.1)
- ◆ Baruvka's Algorithm

Minimum Spanning Tree

Spanning subgraph

- Subgraph of a graph G containing all the vertices of G

Spanning tree

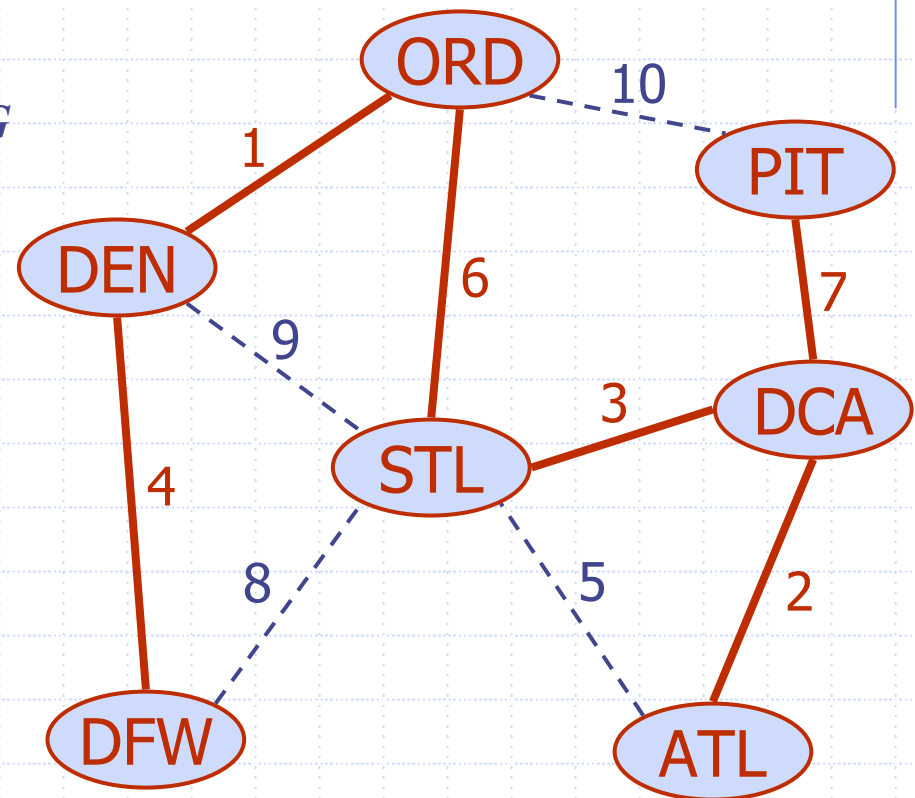
- Spanning subgraph that is itself a (free) tree

Minimum spanning tree (MST)

- Spanning tree of a weighted graph with minimum total edge weight

◆ Applications

- Communications networks
- Transportation networks



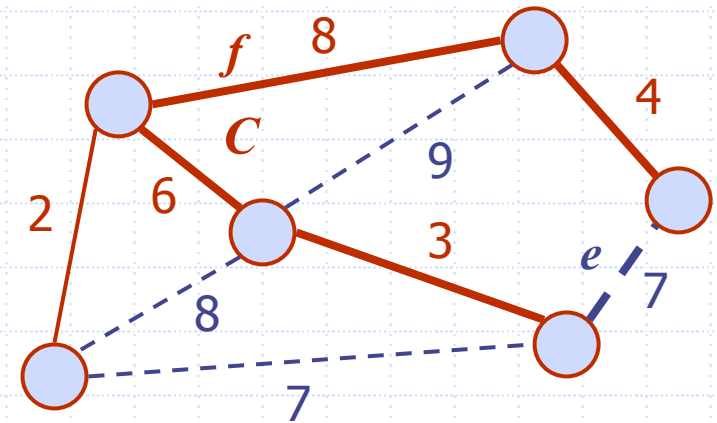
Cycle Property

Cycle Property:

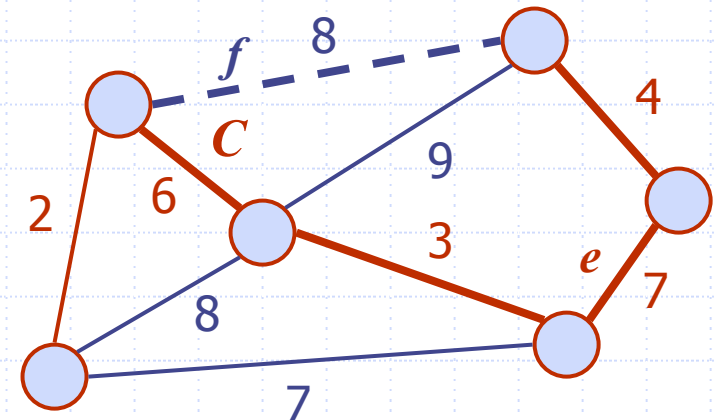
- Let T be a minimum spanning tree of a weighted graph G
- Let e be an edge of G that is not in T and C let be the cycle formed by e with T
- For every edge f of C , $weight(f) \leq weight(e)$

Proof:

- By contradiction
- If $weight(f) > weight(e)$ we can get a spanning tree of smaller weight by replacing e with f



Replacing f with e yields a better spanning tree



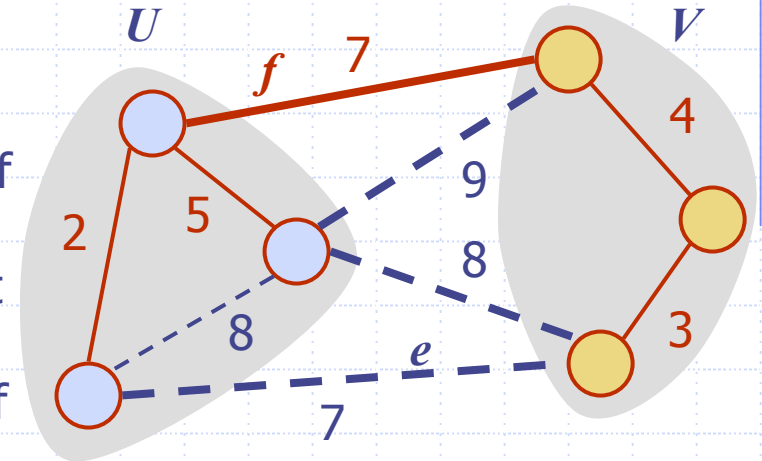
Partition Property

Partition Property:

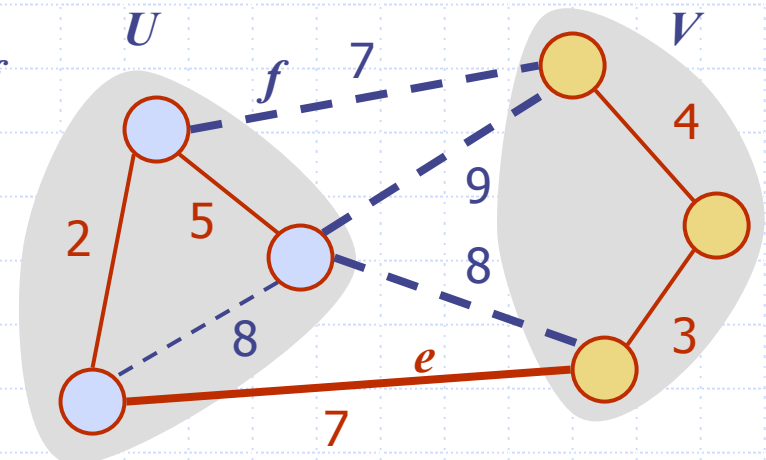
- Consider a partition of the vertices of G into subsets U and V
- Let e be an edge of minimum weight across the partition
- There is a minimum spanning tree of G containing edge e

Proof:

- Let T be an MST of G
- If T does not contain e , consider the cycle C formed by e with T and let f be an edge of C across the partition
- By the cycle property,
 $weight(f) \leq weight(e)$
- Thus, $weight(f) = weight(e)$
- We obtain another MST by replacing f with e

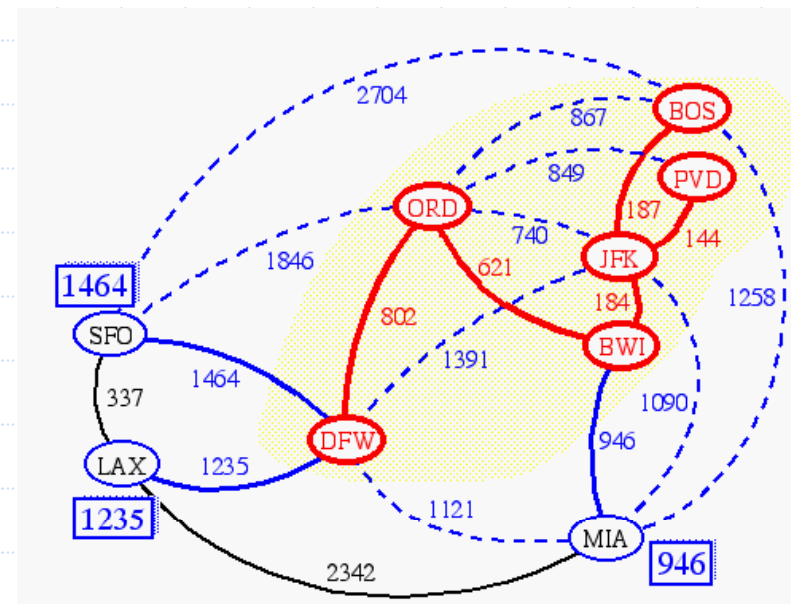


Replacing f with e yields another MST



Prim-Jarnik's Algorithm

- ◆ Similar to Dijkstra's algorithm (for a connected graph)
- ◆ We pick an arbitrary vertex s and we grow the MST as a cloud of vertices, starting from s
- ◆ We store with each vertex v a label $d(v) =$ the smallest weight of an edge connecting v to a vertex in the cloud
- ◆ At each step:
 - We add to the cloud the vertex u outside the cloud with the smallest distance label
 - We update the labels of the vertices adjacent to u

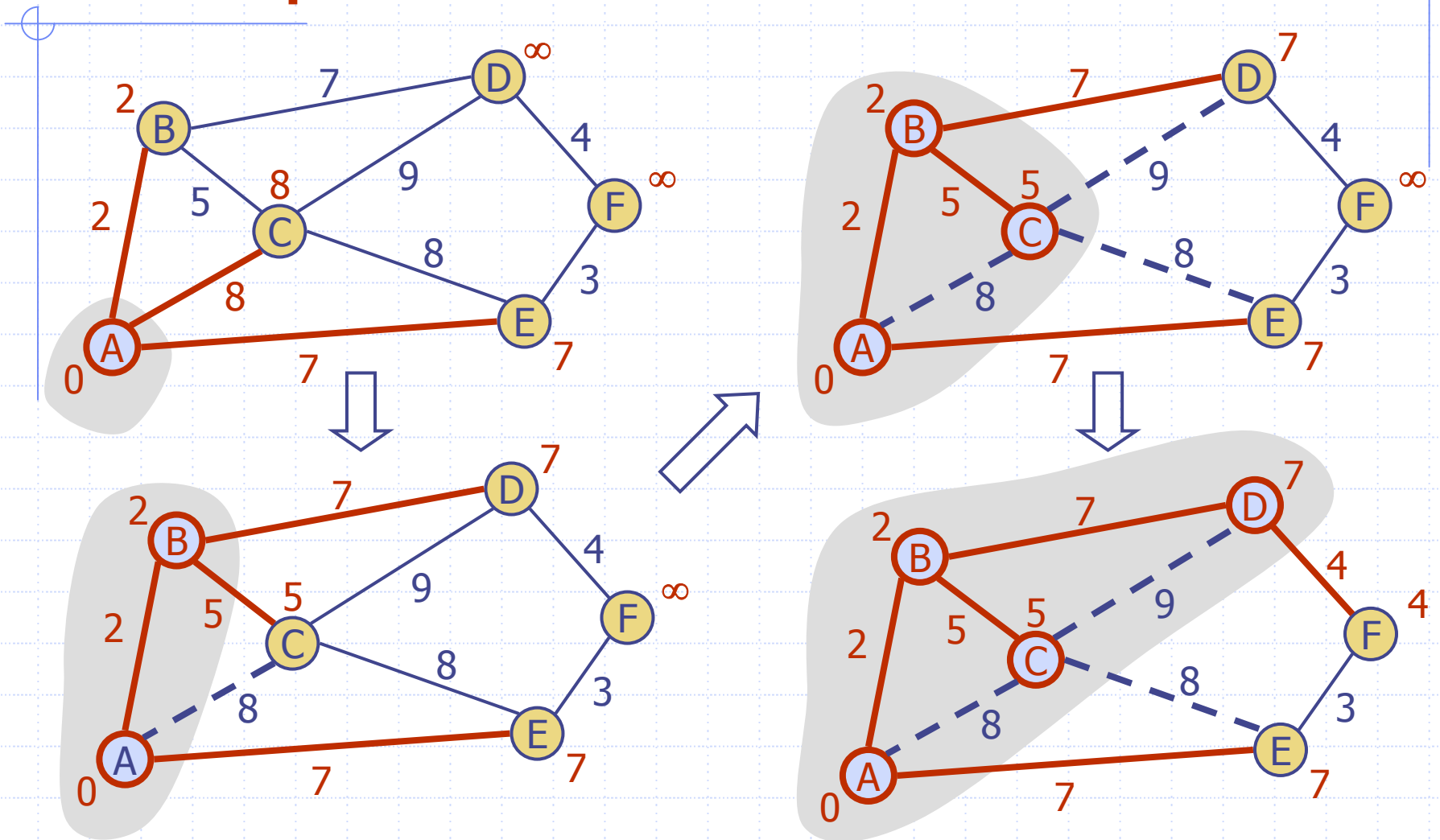


Prim-Jarnik's Algorithm (cont.)

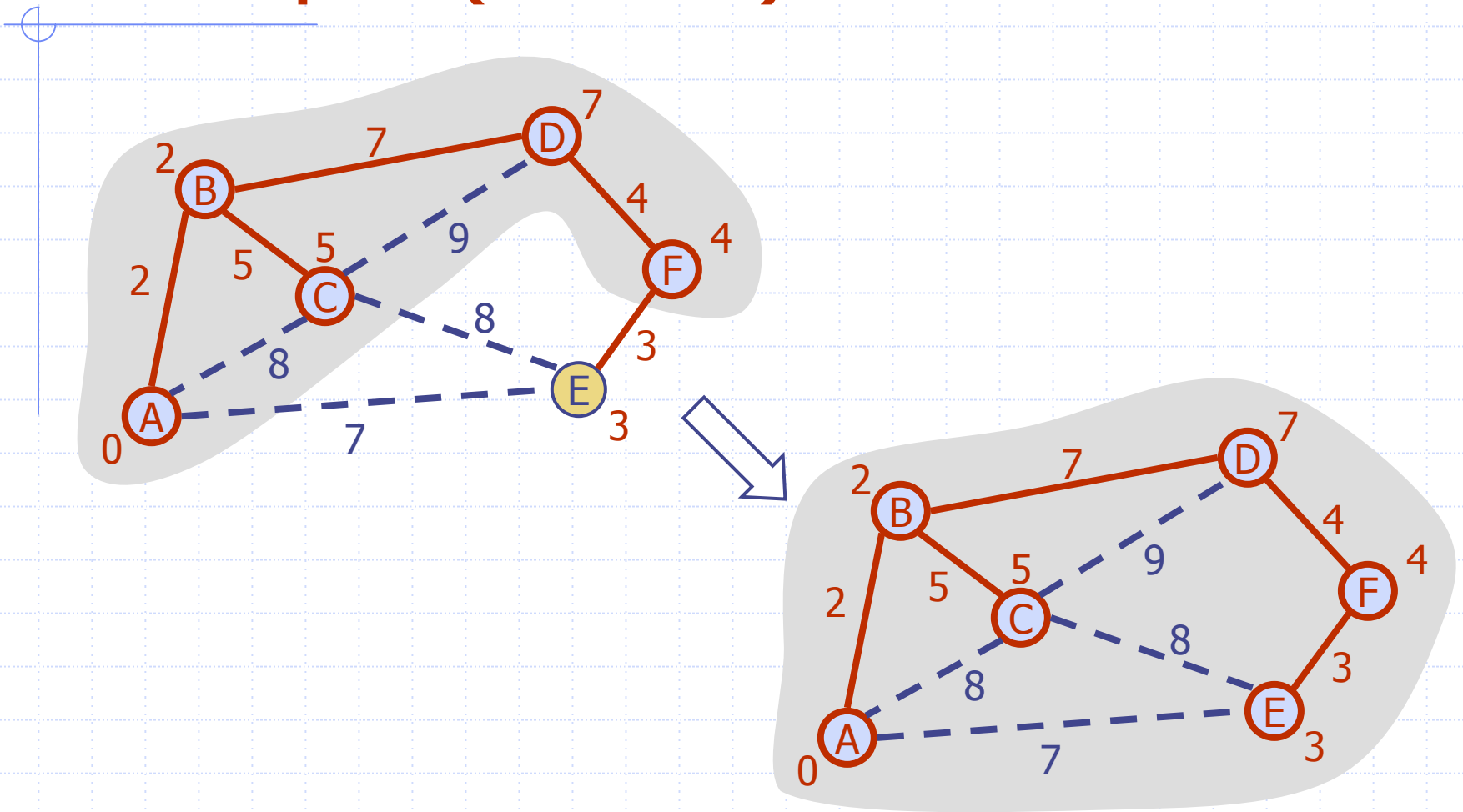
- ◆ A priority queue stores the vertices outside the cloud
 - Key: distance
 - Element: vertex
- ◆ Locator-based methods
 - *insert(k,e)* returns a locator
 - *replaceKey(l,k)* changes the key of an item
- ◆ We store three labels with each vertex:
 - Distance
 - Parent edge in MST
 - Locator in priority queue

```
Algorithm PrimJarnikMST(G)  
   $Q \leftarrow$  new heap-based priority queue  
   $s \leftarrow$  a vertex of  $G$   
  for all  $v \in G.vertices()$   
    if  $v = s$   
      setDistance( $v, 0$ )  
    else  
      setDistance( $v, \infty$ )  
      setParent( $v, \emptyset$ )  
       $l \leftarrow Q.insert(getDistance(v), v)$   
      setLocator( $v, l$ )  
  while  $\neg Q.isEmpty()$   
     $u \leftarrow Q.removeMin()$   
    for all  $e \in G.incidentEdges(u)$   
       $z \leftarrow G.opposite(u, e)$   
       $r \leftarrow weight(e)$   
      if  $r < getDistance(z)$   
        setDistance( $z, r$ )  
        setParent( $z, e$ )  
         $Q.replaceKey(getLocator(z), r)$ 
```

Example



Example (contd.)



Analysis

- ◆ Graph operations
 - Method `incidentEdges` is called once for each vertex
- ◆ Label operations
 - We set/get the distance, parent and locator labels of vertex z $O(\deg(z))$ times
 - Setting/getting a label takes $O(1)$ time
- ◆ Priority queue operations
 - Each vertex is inserted once into and removed once from the priority queue, where each insertion or removal takes $O(\log n)$ time
 - The key of a vertex w in the priority queue is modified at most $\deg(w)$ times, where each key change takes $O(\log n)$ time
- ◆ Prim-Jarnik's algorithm runs in $O((n + m) \log n)$ time provided the graph is represented by the adjacency list structure
 - Recall that $\sum_v \deg(v) = 2m$
- ◆ The running time is $O(m \log n)$ since the graph is connected

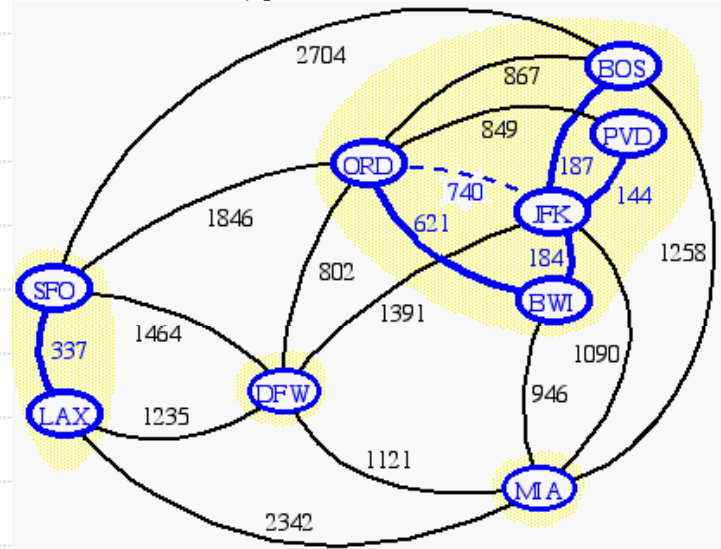
Kruskal's Algorithm

- ◆ A priority queue stores the edges outside the cloud
 - Key: weight
 - Element: edge
- ◆ At the end of the algorithm
 - We are left with one cloud that encompasses the MST
 - A tree T which is our MST

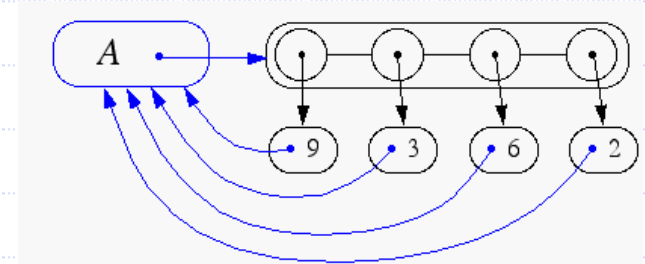
```
Algorithm KruskalMST( $G$ )  
  for each vertex  $V$  in  $G$  do  
    define a Cloud( $v$ ) of  $\leftarrow \{v\}$   
  let  $Q$  be a priority queue.  
  Insert all edges into  $Q$  using their  
  weights as the key  
   $T \leftarrow \emptyset$   
  while  $T$  has fewer than  $n-1$  edges do  
    edge  $e = T.removeMin()$   
    Let  $u, v$  be the endpoints of  $e$   
    if Cloud( $v$ )  $\neq$  Cloud( $u$ ) then  
      Add edge  $e$  to  $T$   
      Merge Cloud( $v$ ) and Cloud( $u$ )  
  return  $T$ 
```

Data Structure for Kruskal Algorithm

- ◆ The algorithm maintains a forest of trees
- ◆ An edge is accepted if it connects distinct trees
- ◆ We need a data structure that maintains a **partition**, i.e., a collection of disjoint sets, with the operations:
 - **find**(u): return the set storing u
 - **union**(u,v): replace the sets storing u and v with their union



Representation of a Partition



- ◆ Each set is stored in a sequence
- ◆ Each element has a reference back to the set
 - operation **find**(u) takes $O(1)$ time, and returns the set of which u is a member.
 - in operation **union**(u, v), we move the elements of the smaller set to the sequence of the larger set and update their references
 - the time for operation **union**(u, v) is $\min(n_u, n_v)$, where n_u and n_v are the sizes of the sets storing u and v
- ◆ Whenever an element is processed, it goes into a set of size at least double, hence each element is processed at most $\log n$ times

Partition-Based Implementation

- ◆ A partition-based version of Kruskal's Algorithm performs cloud merges as unions and tests as finds.

Algorithm *Kruskal(G)*:

Input: A weighted graph G .

Output: An MST T for G .

Let P be a partition of the vertices of G , where each vertex forms a separate set.

Let Q be a priority queue storing the edges of G , sorted by their weights

Let T be an initially-empty tree

while Q is not empty **do**

$(u,v) \leftarrow Q.\text{removeMinElement}()$

if $P.\text{find}(u) \neq P.\text{find}(v)$ **then**

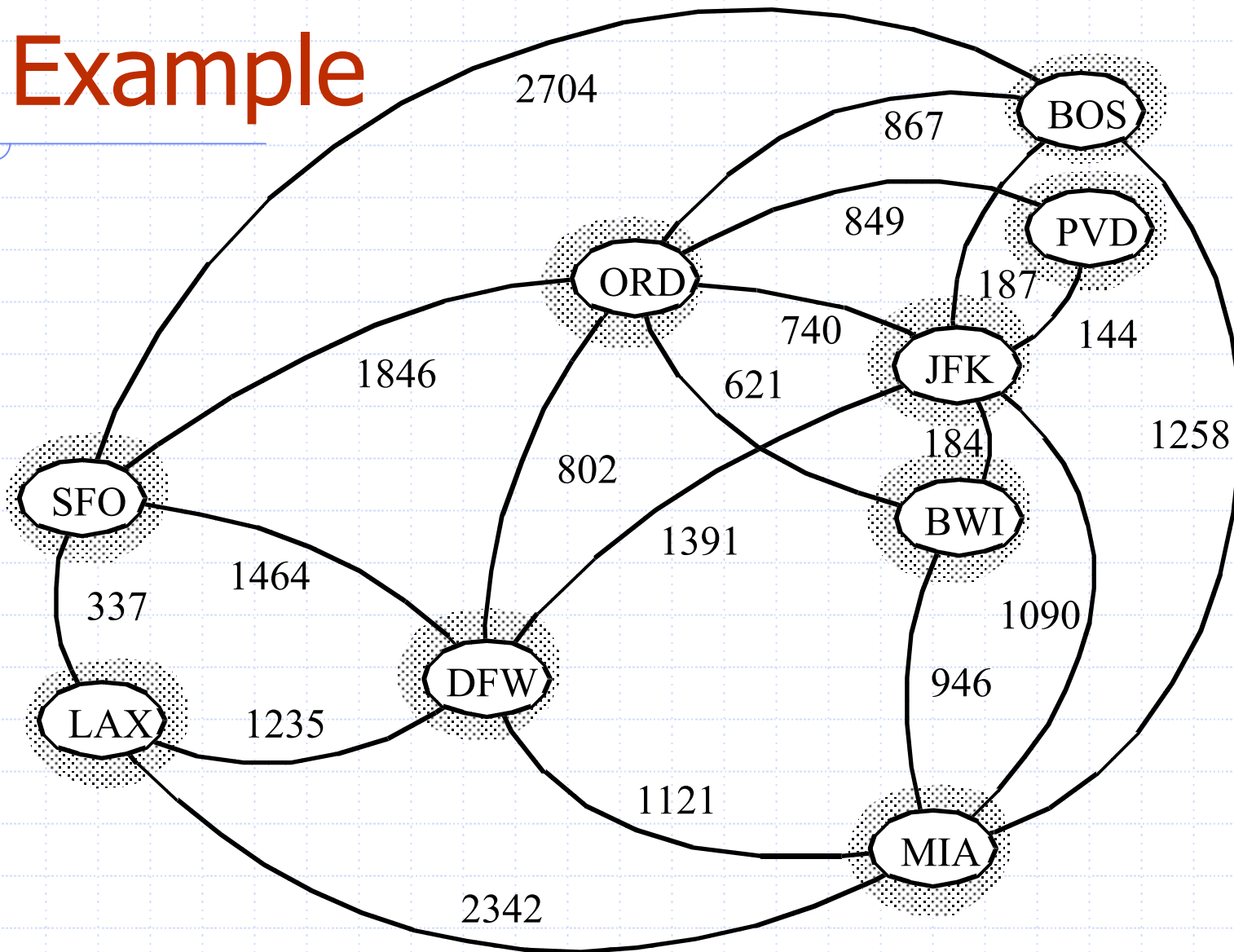
 Add (u,v) to T

$P.\text{union}(u,v)$

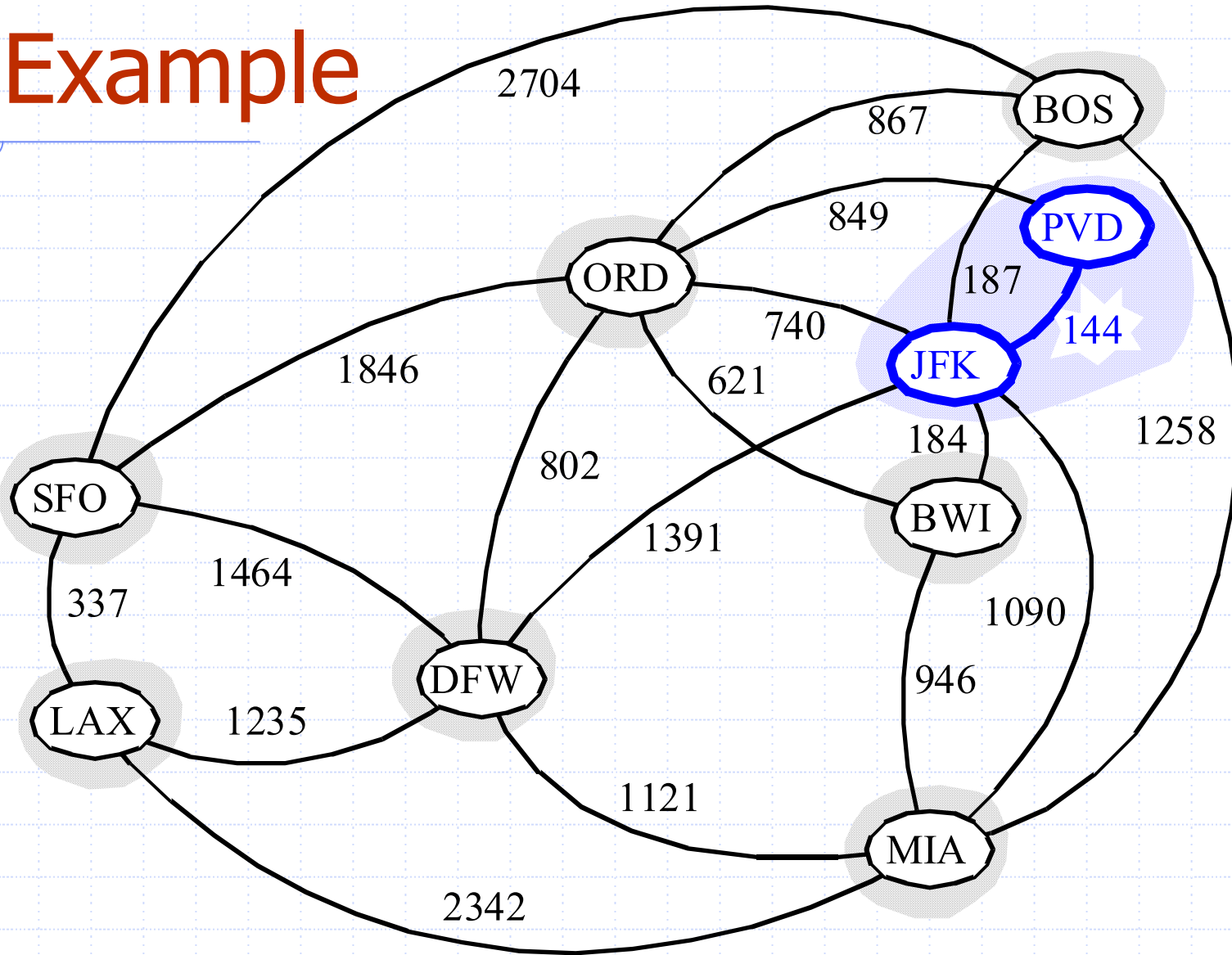
return T

Running time:
 $O((n+m)\log n)$

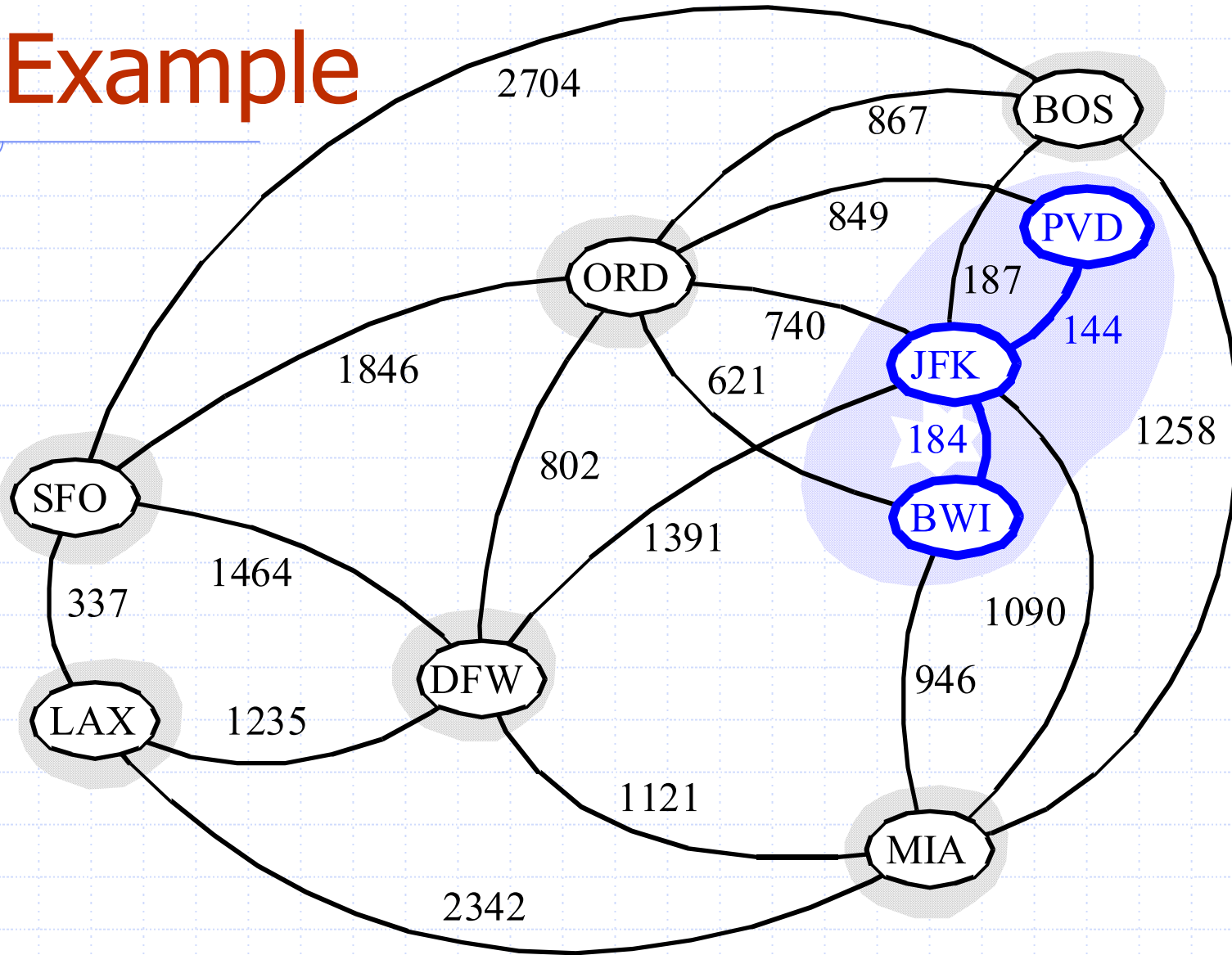
Kruskal Example



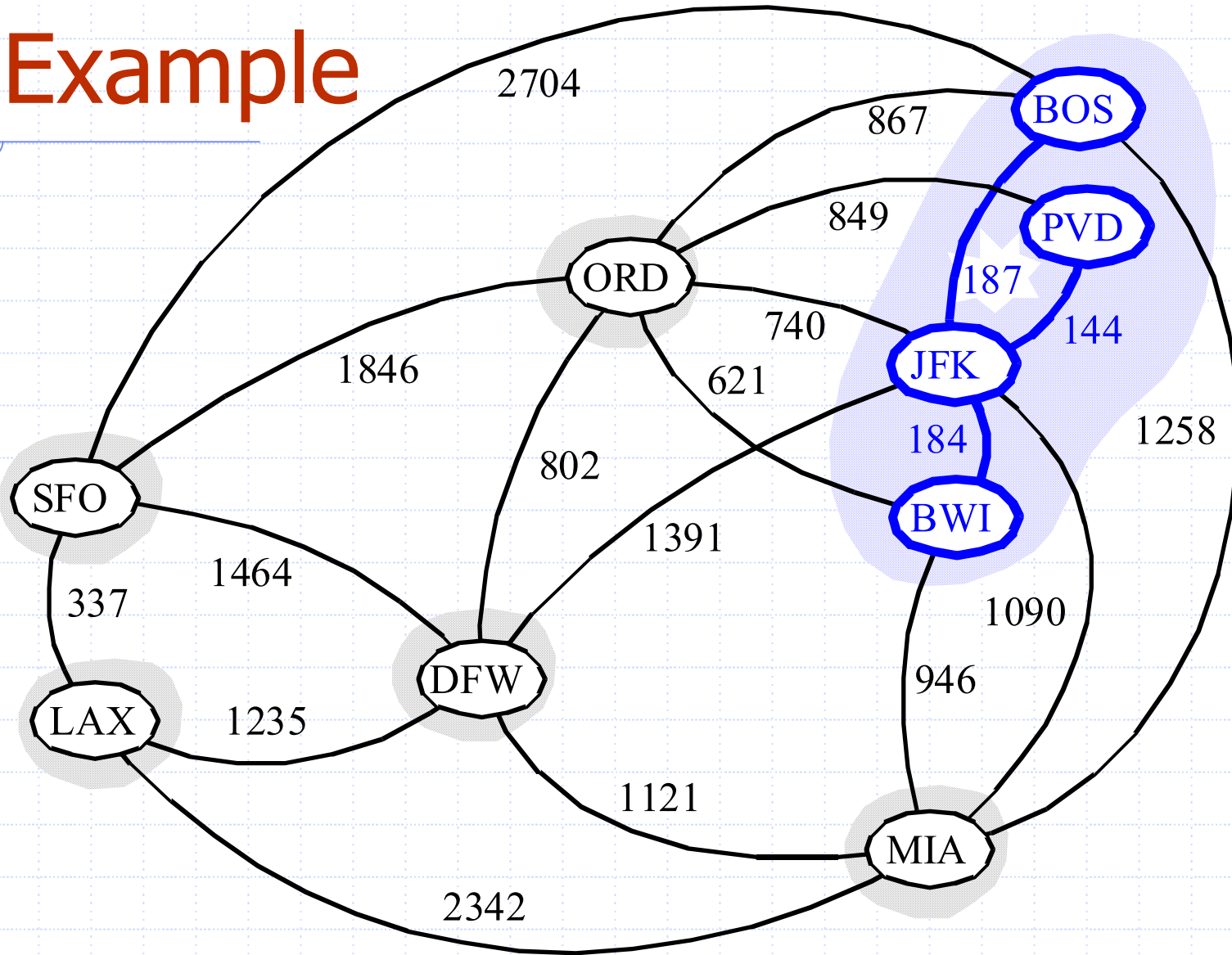
Example



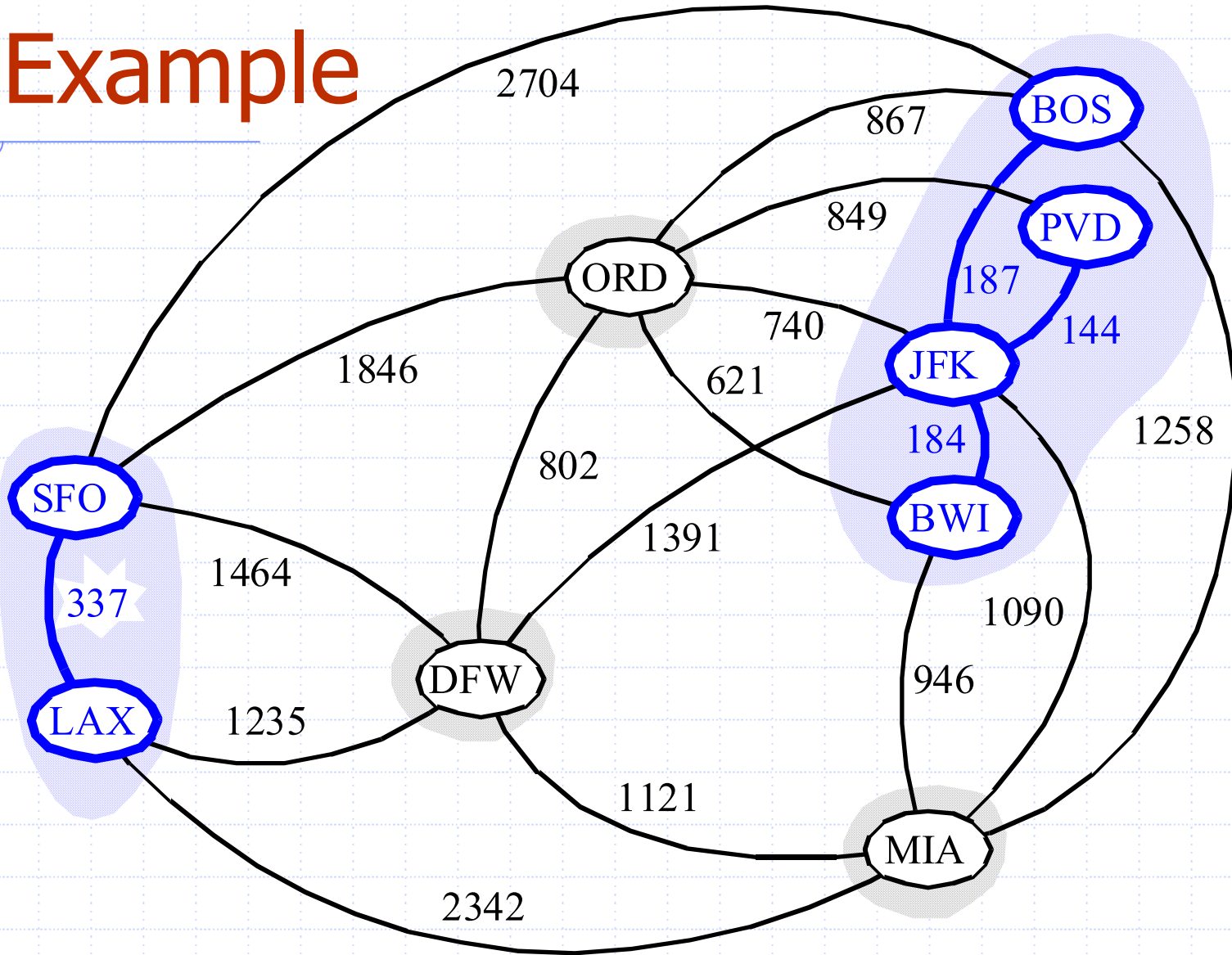
Example



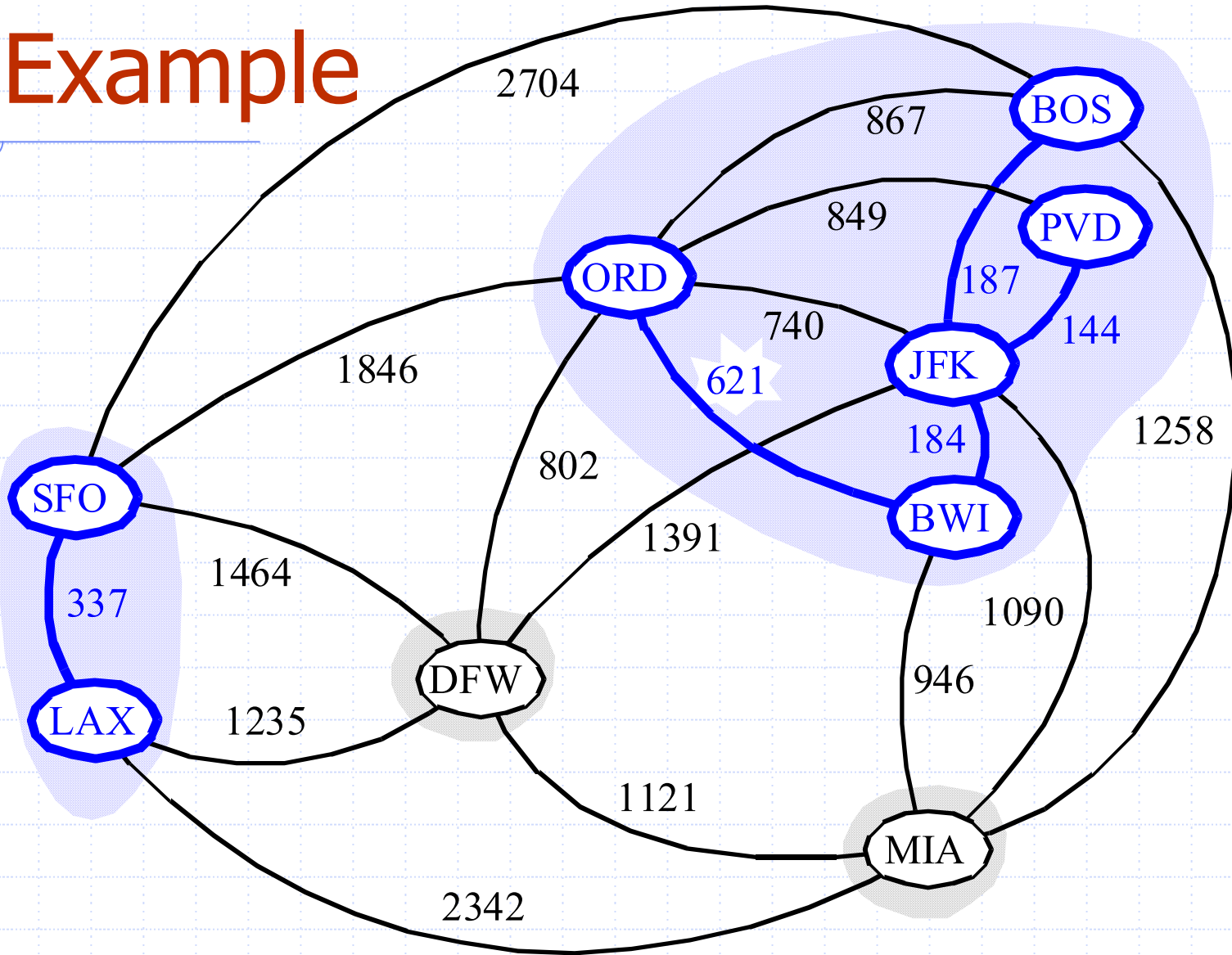
Example



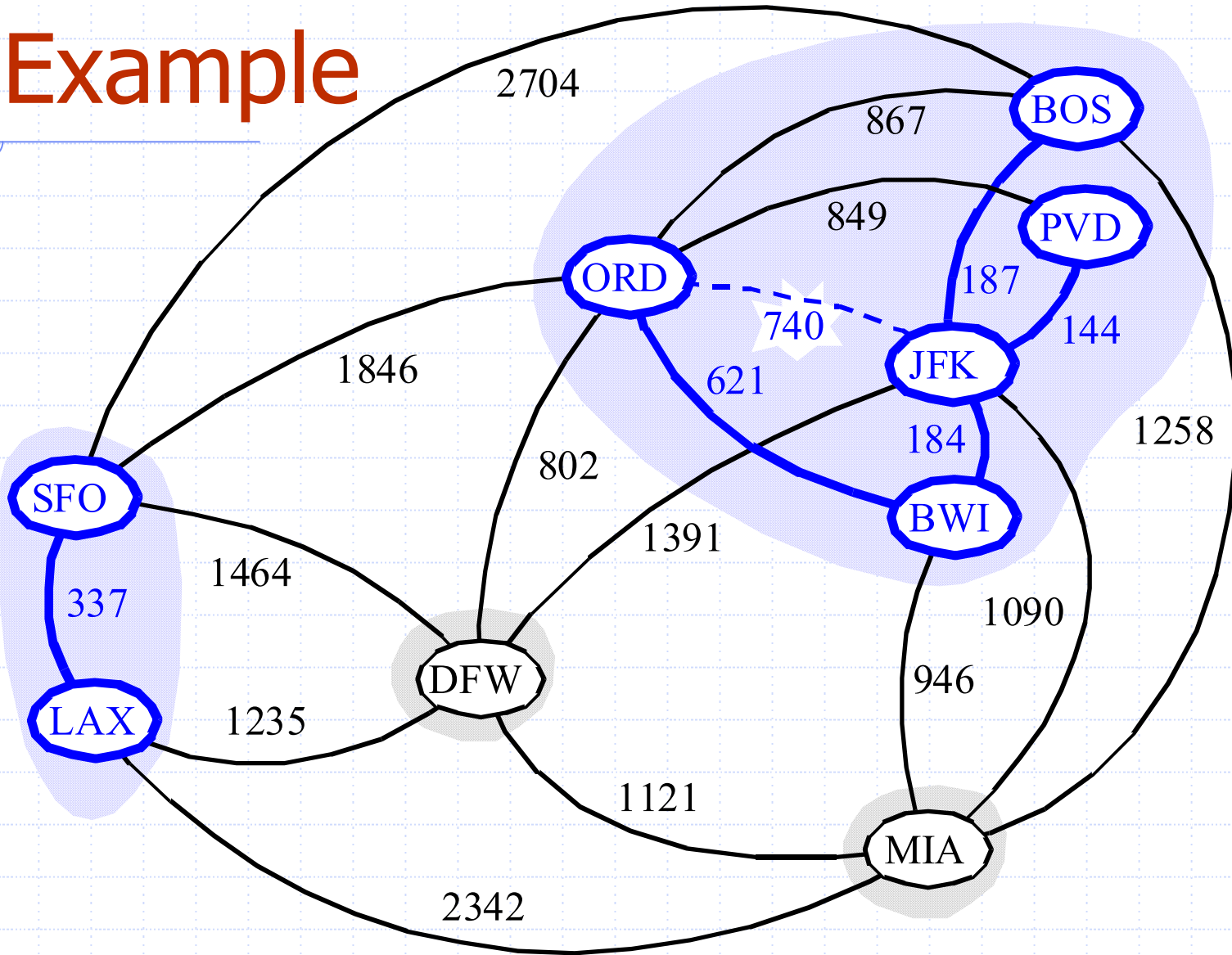
Example



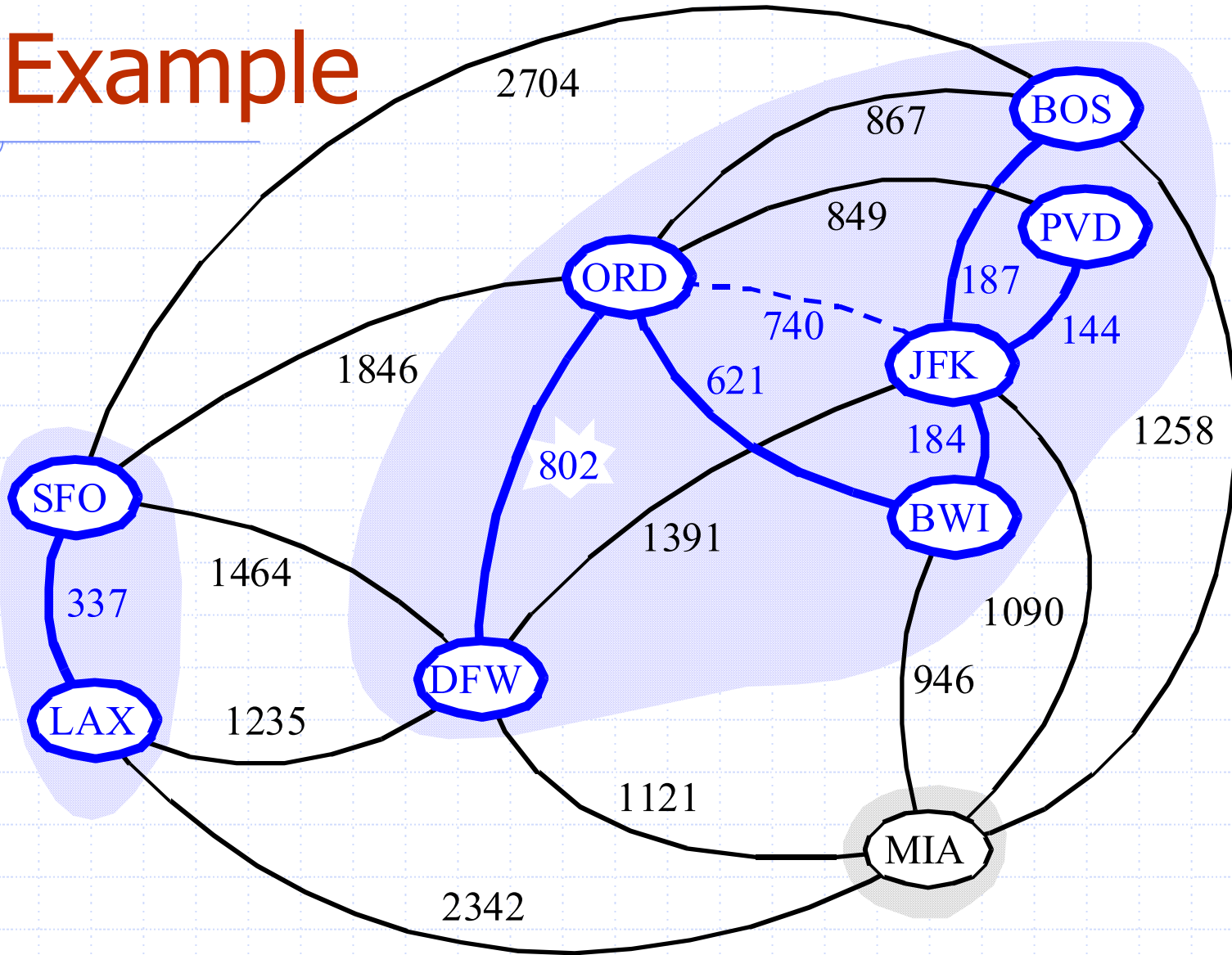
Example



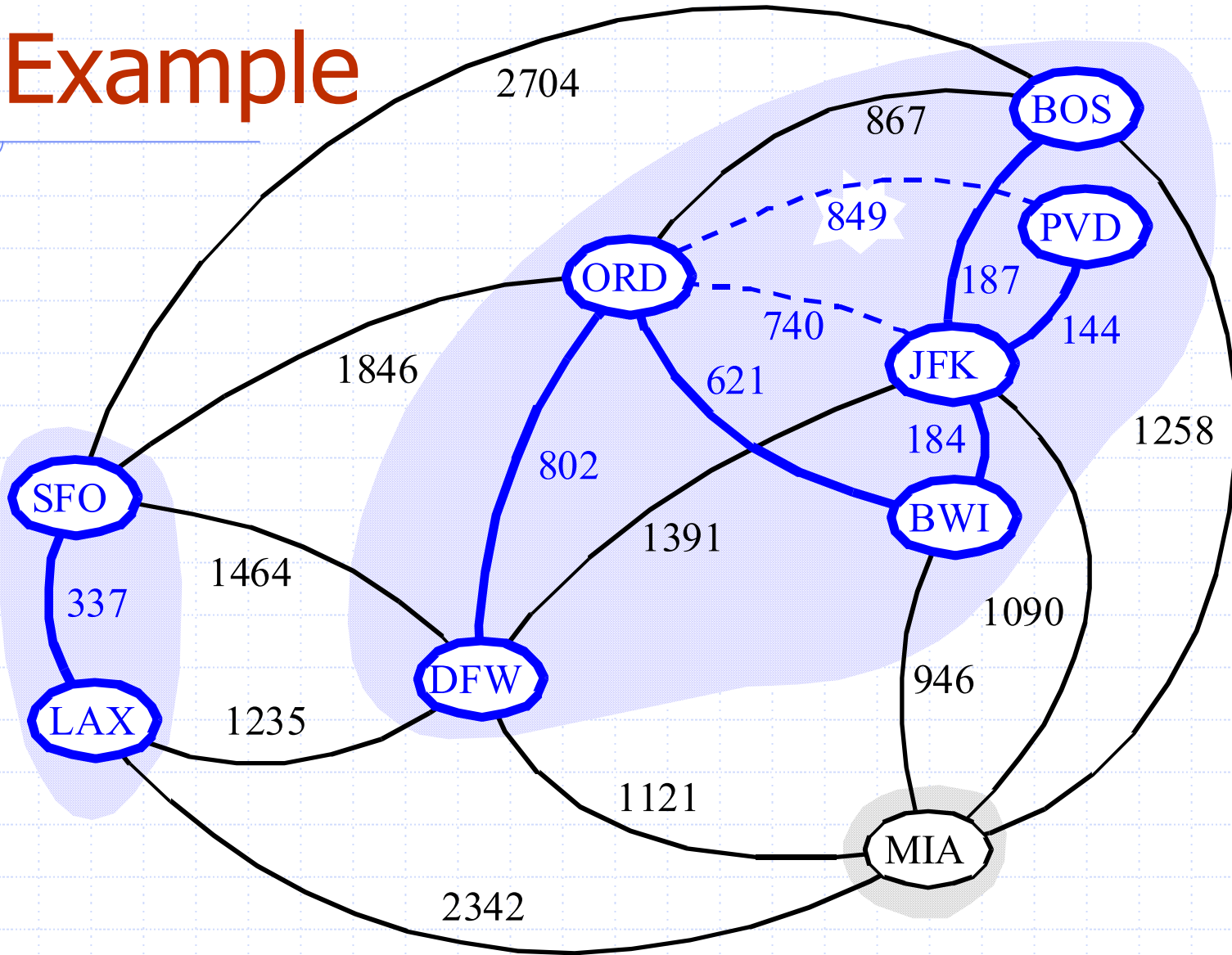
Example



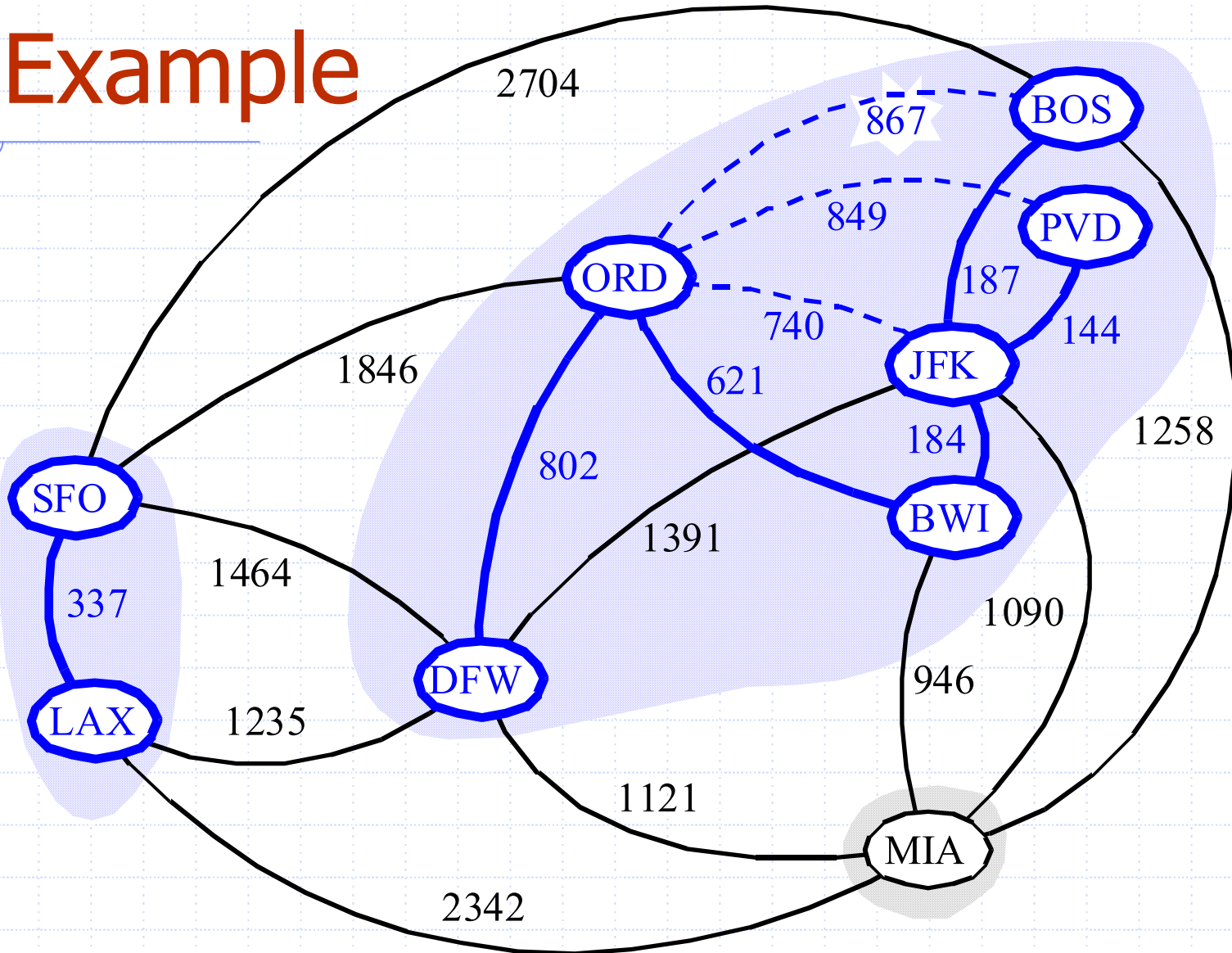
Example



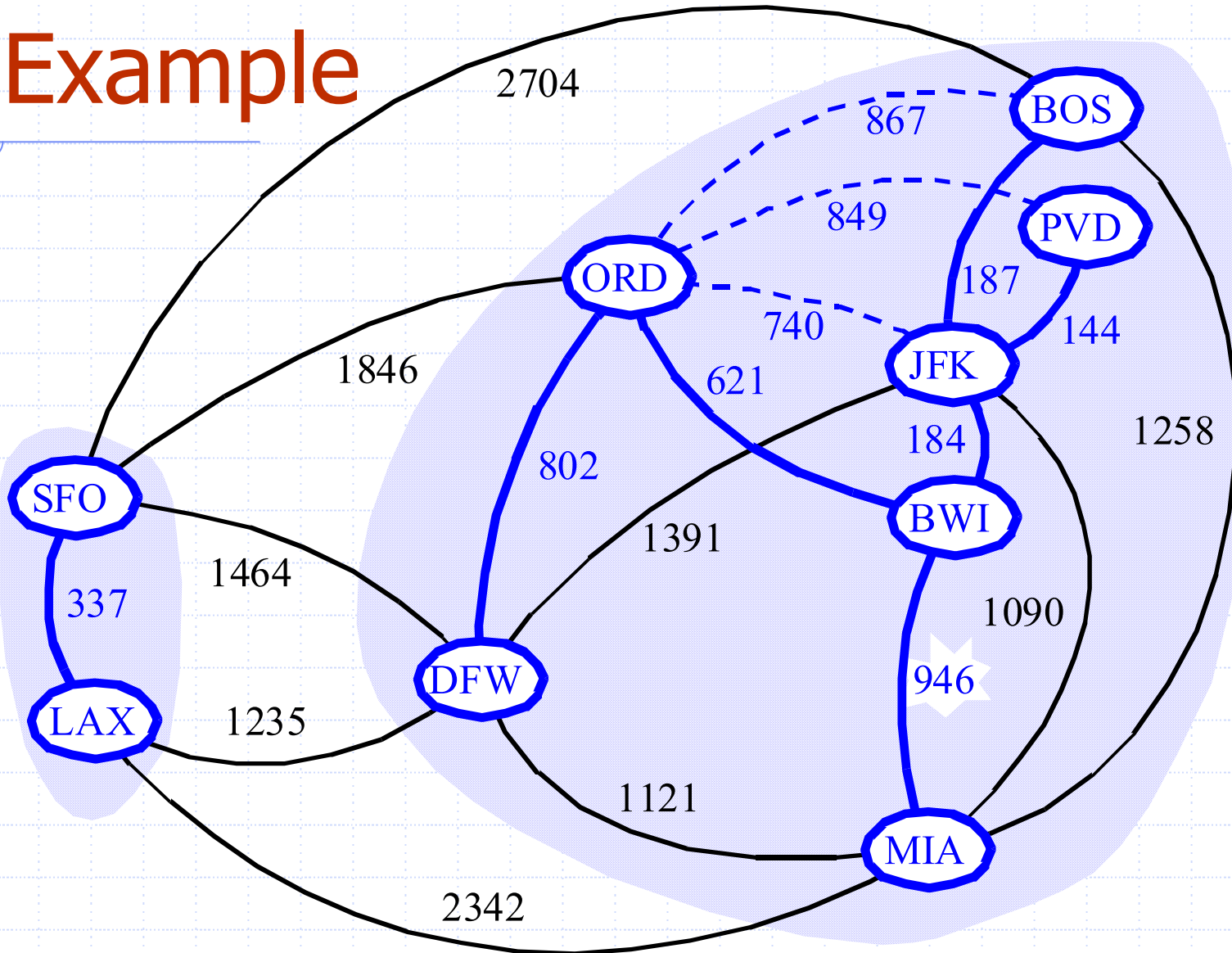
Example



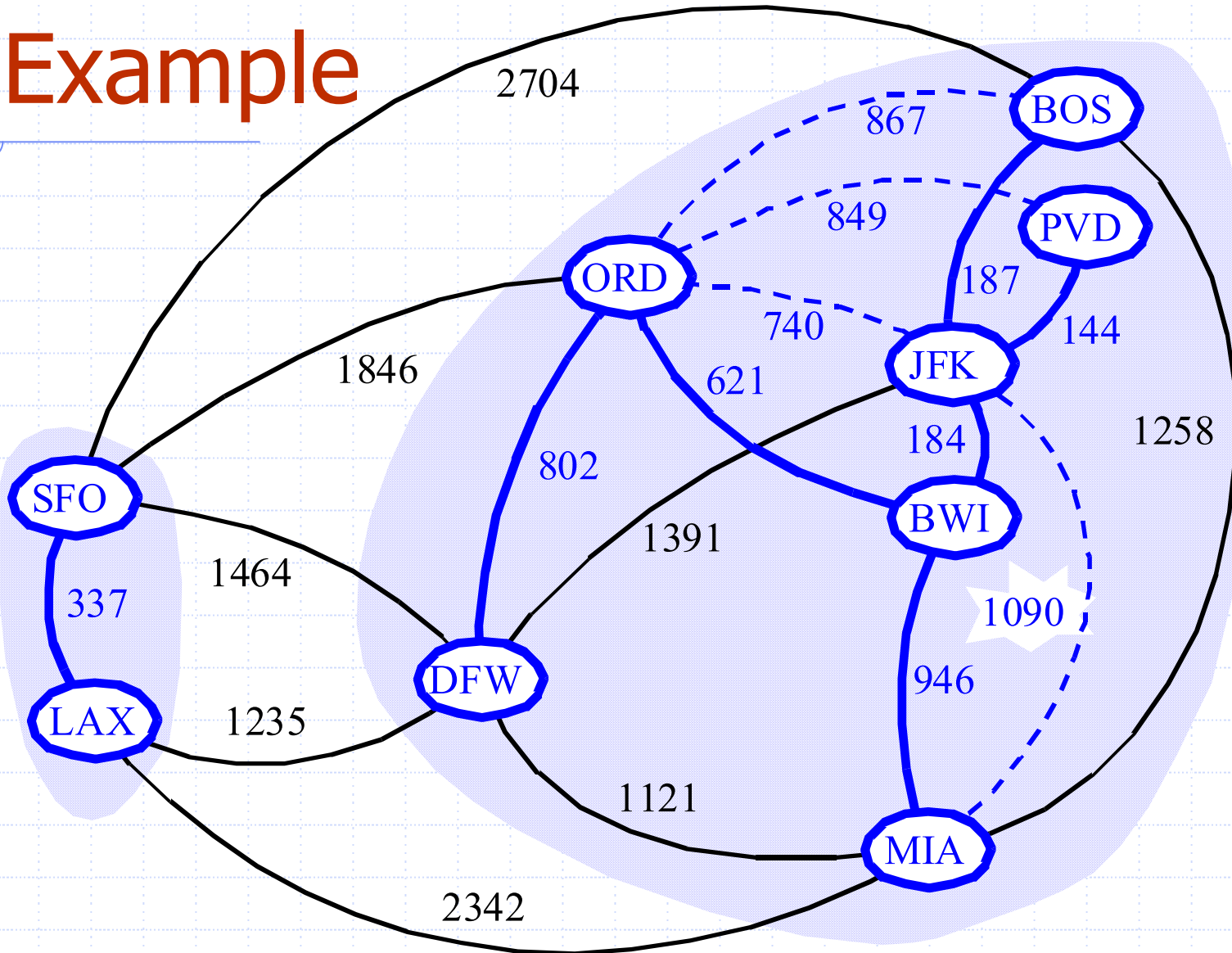
Example



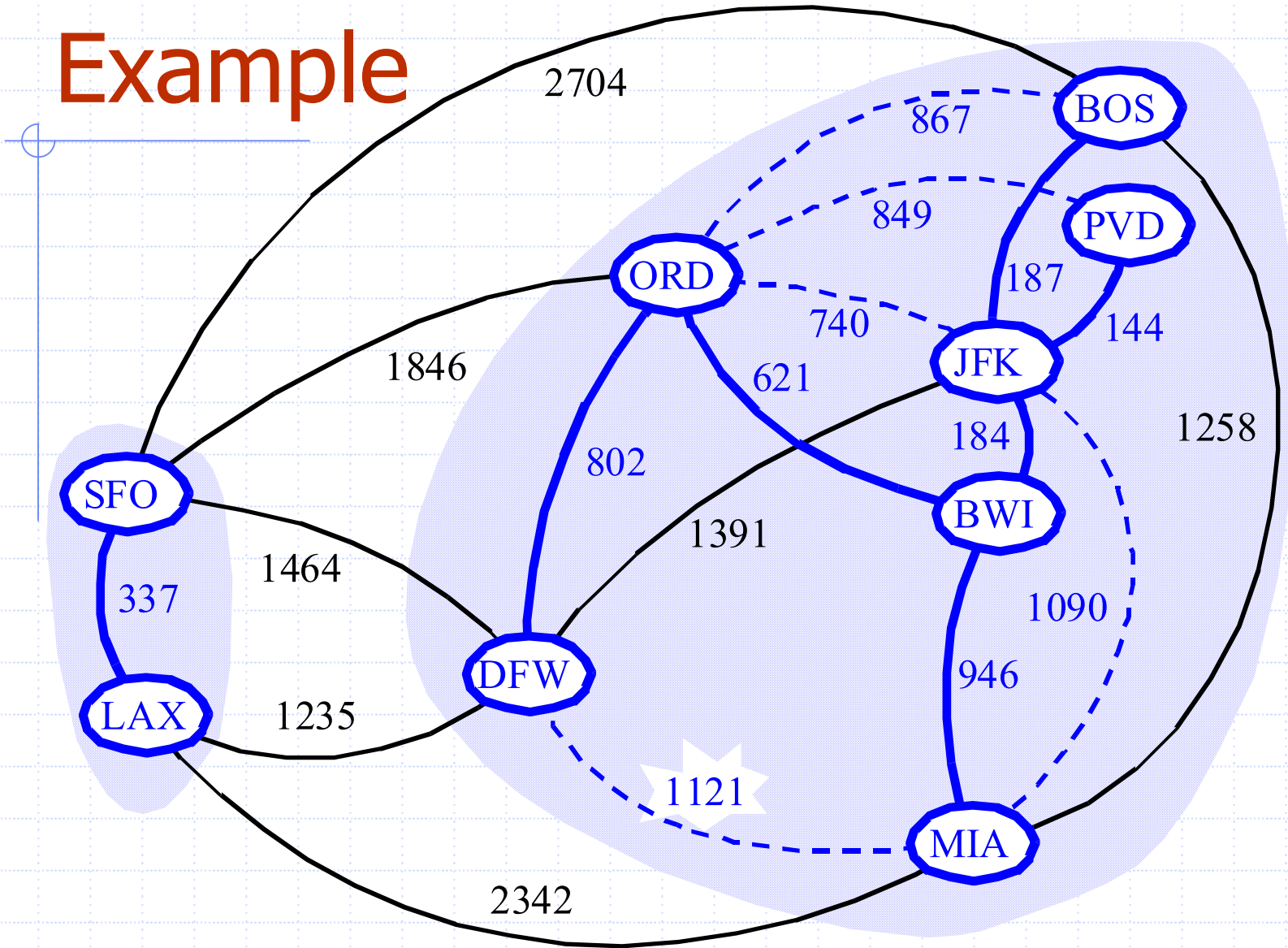
Example



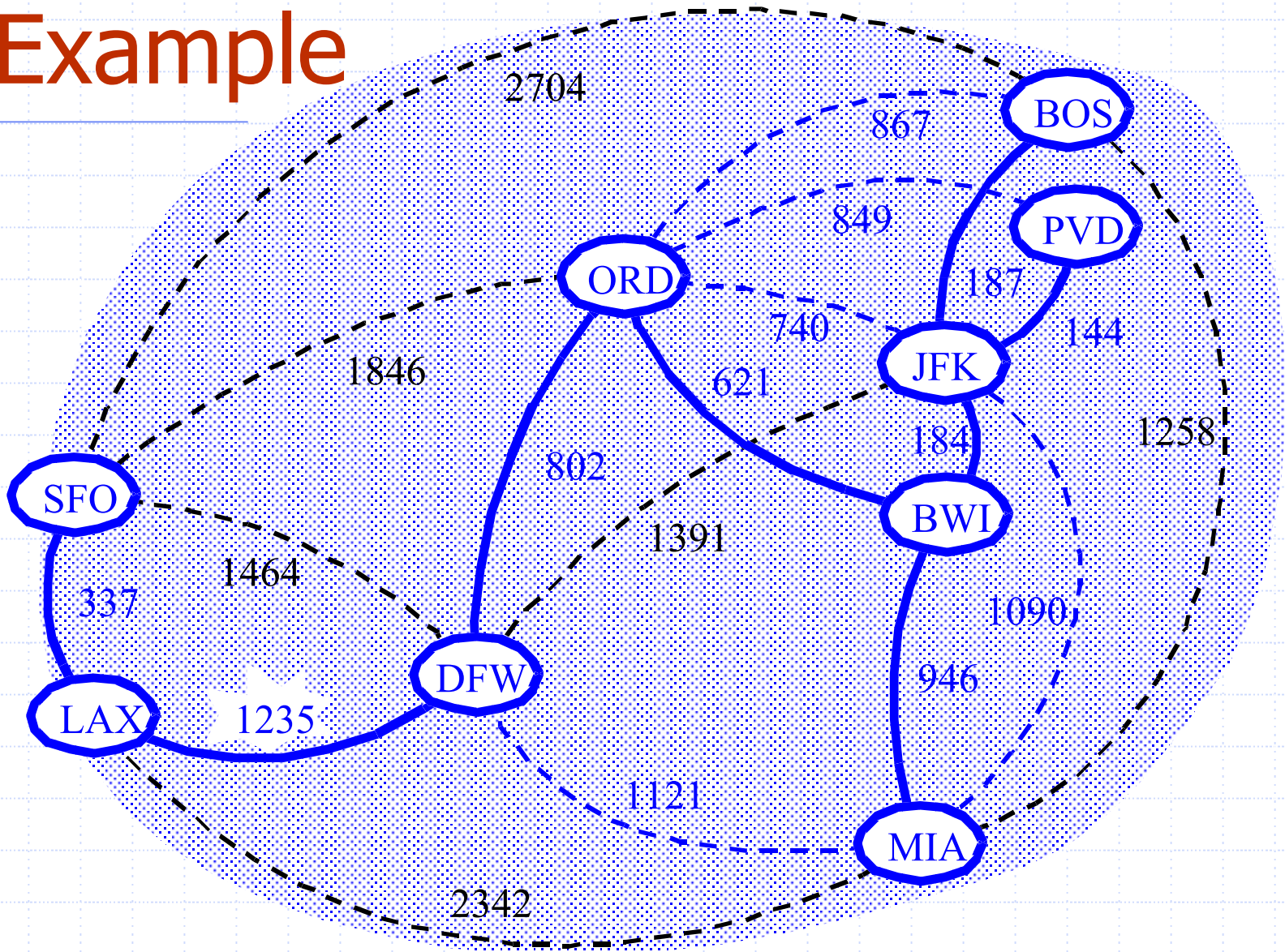
Example



Example



Example



Baruvka's Algorithm

- ◆ Like Kruskal's Algorithm, Baruvka's algorithm grows many "clouds" at once.

Algorithm *BaruvkaMST*(G)

$T \leftarrow V$ {just the vertices of G }

while T has fewer than $n-1$ edges **do**

for each connected component C in T **do**

 Let edge e be the smallest-weight edge from C to another component in T .

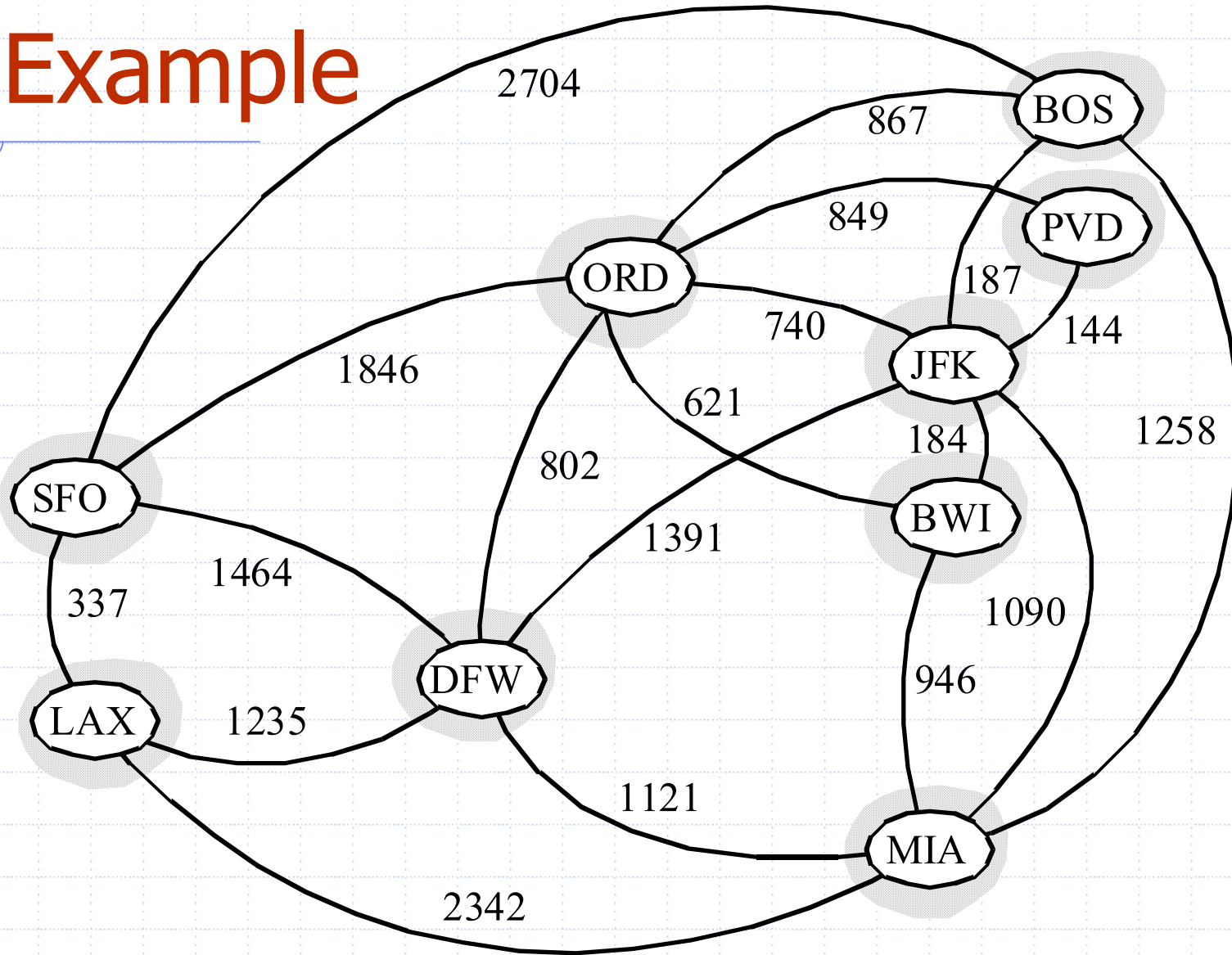
if e is not already in T **then**

 Add edge e to T

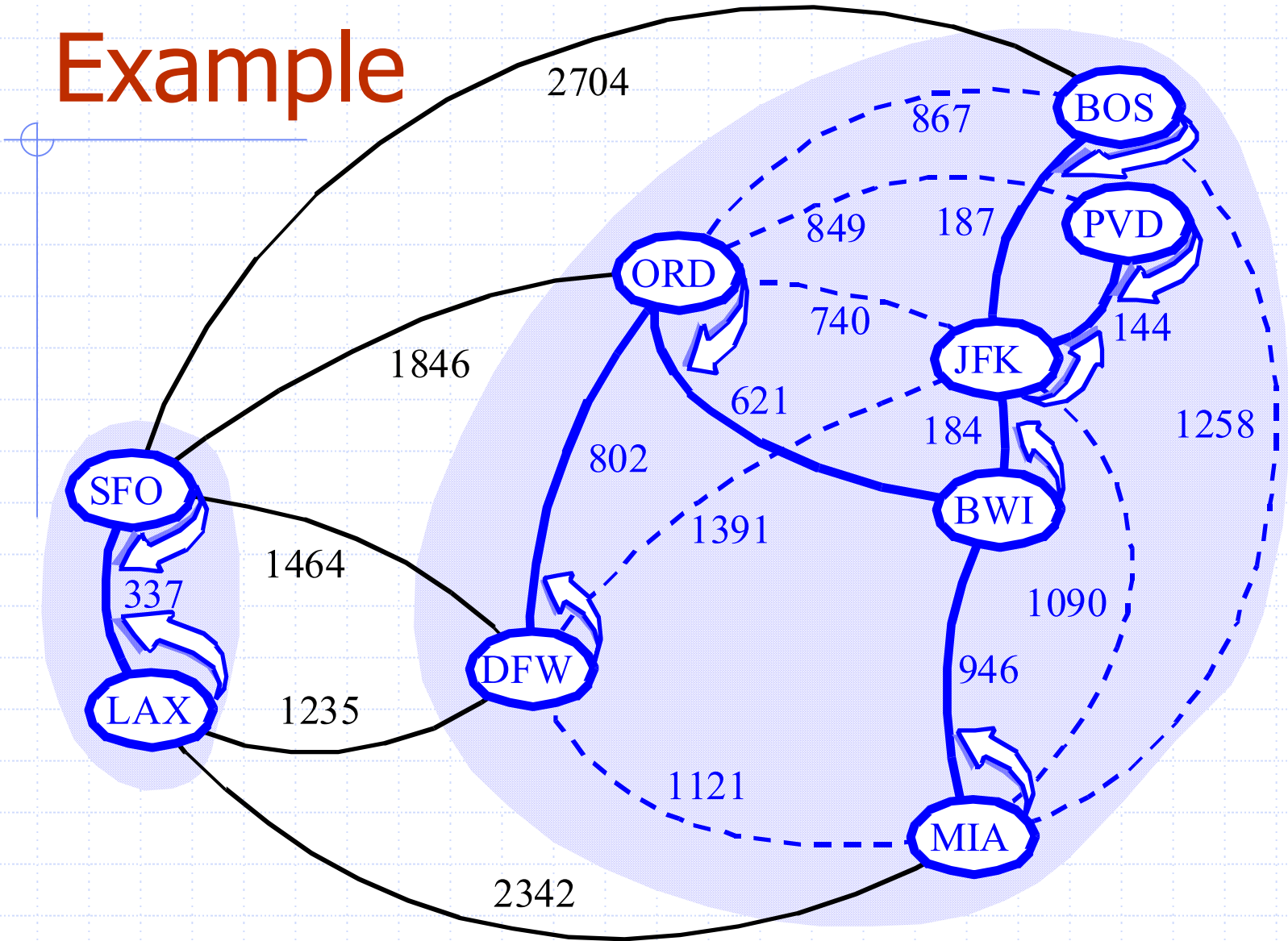
return T

- ◆ Each iteration of the while-loop halves the number of connected components in T .
 - The running time is $O(m \log n)$.

Baruvka Example



Example



Example

